

Runge-Kutta

```
void simulation::UpdateRungeKutta(double h){
    particle *part;

    ClearAccelerations();
    for (forces.MoveFirst(); !forces.AtEnd(); forces.MoveNext()){
        forces.GetCurrent()->CalculateForce();
    }
    DivideByMass();
    HandleFixed();

    int i;
    for (particles.MoveFirst(), i = 0; !particles.AtEnd(); particles.MoveNext(), i++){
        part = particles.GetCurrent();
        p[0][i] = part->position;
        v[0][i] = part->velocity;
        a[0][i] = part->acceleration;
    }

    for (particles.MoveFirst(), i = 0; !particles.AtEnd(); particles.MoveNext(), i++){
        part = particles.GetCurrent();
        part->position += v[0][i] * h/2;
        part->velocity += a[0][i] * h/2;
        p[1][i] = part->position;
        v[1][i] = part->velocity;
        a[1][i] = part->acceleration;
    }

    ClearAccelerations();
    for (forces.MoveFirst(); !forces.AtEnd(); forces.MoveNext())
        forces.GetCurrent()->CalculateForce();
    DivideByMass();
    HandleFixed();

    for (particles.MoveFirst(), i = 0; !particles.AtEnd(); particles.MoveNext(), i++){
        part = particles.GetCurrent();
        part->position += v[1][i] * h/2;
        part->velocity += a[1][i] * h/2;
        p[2][i] = part->position;
        v[2][i] = part->velocity;
        a[2][i] = part->acceleration;
    }

    ClearAccelerations();
    for (forces.MoveFirst(); !forces.AtEnd(); forces.MoveNext())
        forces.GetCurrent()->CalculateForce();
    DivideByMass();
    HandleFixed();

    for (particles.MoveFirst(), i = 0; !particles.AtEnd(); particles.MoveNext(), i++){
        part = particles.GetCurrent();
        part->position += v[2][i] * h;
        part->velocity += a[2][i] * h;
        p[3][i] = part->position;
        v[3][i] = part->velocity;
        a[3][i] = part->acceleration;
    }

    ClearAccelerations();
```

Runge-Kutta

```
for (forces.MoveFirst(); !forces.AtEnd(); forces.MoveNext())
    forces.GetCurrent()->CalculateForce();
DivideByMass();
HandleFixed();

for (particles.MoveFirst(), i = 0; !particles.AtEnd(); particles.MoveNext(), i++)
{
    part = particles.GetCurrent();
    part->position = p[0][i] + ( ( v[0][i] + (2 * v[1][i]) + (2*v[2][i]) +
        v[3][i] ) / 6 ) * h;
    part->velocity = v[0][i] + ( ( a[0][i] + (2 * a[1][i]) + (2*a[2][i]) +
        a[3][i] ) / 6 ) * h;
}

HandleGround();
}
```