

# Linear Interpolator

```
point LinearInterp::pointOnCurve(double s){
    // ***--- find the interval by the floor of s ---***
    int interval = s;

    // ***--- if s is less than zero return the first point ---***
    if(s < keys[0].t){
        keys[0].p;
    }
    //***--- if s is greater than the last point return the last point---***
    else if(s > keys[nKeys-1].t ){
        keys[nKeys-1].p;
    }

    // ***--- % along the curve is the decimal value of s ---***
    double percentage = s - interval;

    // ***--- Linear Interpolation calculation ---***
    return keys[interval].p + (percentage * (keys[interval+1].p - keys[interval].p));
}

point Interpolator::Evaluate(double t) {
    int i = FindInterval(t);

    if(nKeys < 2){
        return pointOnCurve(0);
    }else if (!keys[i].constant){
        // Calculate s which is the % along and add to it i which is the interval
        double s = ((t-keys[i].t) / ( keys[i+1].t - keys[i].t )) + i;

        return pointOnCurve(s);
    }
    else
    {
        double s = 0;

        double speed = (keys[i+1].dist - keys[i].dist) / ( keys[i+1].t - keys[i].t);
        double distance = keys[i].dist + (t - keys[i].t) * speed;

        int found = 0;

        while (distTable[found].d < distance){
            found++;
        }

        s = distTable[found].s + ( ( distance - distTable[found].d) /
            (distTable[found+1].d - distTable[found].d) ) *
            (distTable[found+1].s - distTable[found].s );

        return (pointOnCurve(s));
    }
}
```